

and Fa_0 produce the cross-reconstructed image Cri_1 , while inputs C_0 and Fa_1 generate the cross-reconstructed image Cri_0 .

2 The Network Details of Training Stage 2

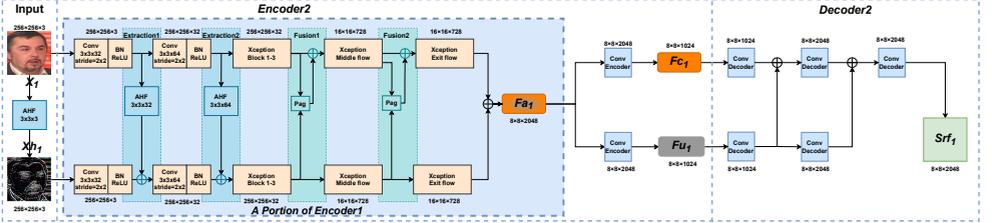


Figure 2: The architecture details of $Encoder_2$ and $Decoder_2$ in our proposed method. (Left) In $Encoder_2$ of training stage 2, a branch first utilizes $Encoder_1$ to extract all forgery semantics for extracting common forgery semantics. (Right) In $Decoder_2$, both branches solely employ convolutional layers to reconstruct forgery semantics.

Encoder₂. In $Encoder_2$, we utilize a portion of $Encoder_1$ responsible for extracting all forgery semantics to extract all forgery semantics, and then employ convolutional layers further disentangle these semantics into unique and common forgery semantics. Figure 2 illustrates the process for inputs X_1 and Xh_1 , obtaining unique forgery semantics Fu_1 and common forgery semantics Fc_1 . Similarly, for inputs X_0 and Xh_0 , we obtain unique forgery semantics Fu_0 and common forgery semantics Fc_0 .

Decoder₂. In $Decoder_2$, we designed two dual-channel networks, each comprising only convolutional decoders, and merged them during the process to reconstruct image semantics. Figure 2 illustrates the process for input Fc_1 and Fu_1 to obtain self-reconstructed image semantics Srf_1 . Consistently, for inputs Fc_0 and Fu_0 , we obtain self-reconstructed image semantics Srf_0 . Additionally, inputs Fc_1 and Fu_0 yield cross-reconstructed image semantics Cri_1 , while inputs Fc_0 and Fu_1 yield cross-reconstructed image semantics Cri_0 .

References

- [1] François Chollet. Xception: Deep learning with depthwise separable convolutions. In *Proceedings of the IEEE conference on computer vision and pattern recognition*, pages 1251–1258, 2017.
- [2] Abdelrahman Shaker, Muhammad Maaz, Hanoona Rasheed, Salman Khan, Ming-Hsuan Yang, and Fahad Shahbaz Khan. Swiftformer: Efficient additive attention for transformer-based real-time mobile vision applications. In *Proceedings of the IEEE/CVF International Conference on Computer Vision*, pages 17425–17436, 2023.