

Supplementary Material

SAM Helps SSL: Mask-guided Attention Bias for Self-supervised Learning

Kensuke Taguchi*¹
kensuke.taguchi.xm@kyocera.jp

Takehiko Kawai*¹
takehiko.kawai.yb@kyocera.jp

Wataru Imaeda¹
wataru.imaeda.xm@kyocera.jp

Hironobu Fujiyoshi²
fujiyoshi@isc.chubu.ac.jp

¹ KYOCERA Corporation, Japan

² Chubu University, Japan

*Equal contribution

A Training Details

A.1 DINO

Loss function. As the baseline CL method, we selected DINO [1], a self-distillation method that feeds multiple views of an image to two encoders. DINO reinterprets the embeddings as the logits of a clustering model, defined by a set of learned “prototypes.” DINO’s loss function is defined as

$$L^{cl}(\mathbf{z}, \mathbf{z}') = H(P(\mathbf{z}), P'(\mathbf{z}')), \quad (1)$$

where $H(a, b) = -a \log b$. Given an input image x , the auxiliary head’s output probability distributions over k dimensions are denoted as P and P' . They are obtained by softmax normalization as

$$P(\mathbf{z})^{(i)} = \frac{\exp(\mathbf{z}^{(i)} / \tau)}{\sum_{k=1}^K \exp(\mathbf{z}^{(k)} / \tau)}, \quad (2)$$

$$P'(\mathbf{z}')^{(i)} = \frac{\exp((\mathbf{z}'^{(i)} - o) / \tau')}{\sum_{k=1}^K \exp(\mathbf{z}'^{(k)} - o) / \tau'}, \quad (3)$$

where $\tau, \tau' > 0$ are the temperature parameters that control the sharpness of the output distribution and o is a centering parameter that prevents one dimension from dominating, thereby preventing collapse.

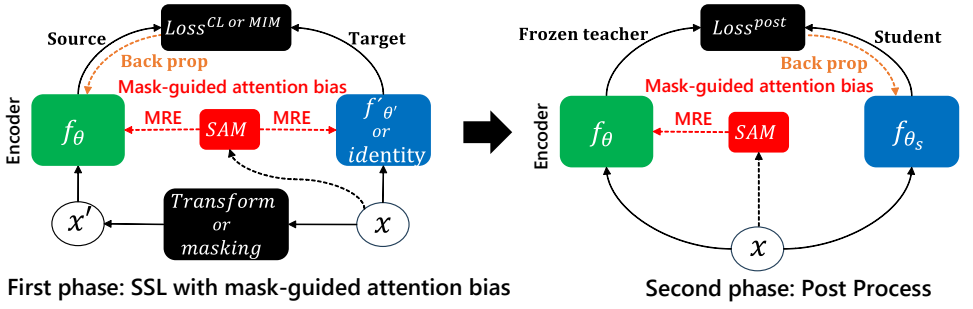


Figure 1: Overview of our method. f_θ be a ViT encoder with mask-guided attention bias and f_{θ_s} be a post-processed ViT student model encoder that does not take mask token vectors.

As post-processing for DINO with mask-guided attention bias in the second phase shown in Fig 1, we used the loss function proposed by RoB [4]. This is defined as

$$L_{cl}^{kd}(\mathbf{z}_s, \mathbf{z}) = H(P(\mathbf{z}_s), P(\mathbf{z})). \quad (4)$$

Note that Eq. (4) does not include a centering parameter as a collapse-preventing regularization term. The implementation details of post-processing in the second phase use the same settings as in the first phase.

Implementation details. Table 1 shows the implementation details of DINO alone and DINO with mask-guided attention bias in the first phase shown in Fig 1. We basically follow Caron *et al.* [4], except that we changed the base learning rate to 2.5e-3, five times the original rate for ImageNet100. We use the linear lr scaling rule [4]: $lr = base_lr \times \frac{batchsize}{256}$. For training stability, we froze the mask-guided attention bias parameters during the first 100 epochs as a warm-up. Tables 3 and 5 show the evaluation settings for linear probing and full-data fine-tuning, which are same as in Caron *et al.* [4]. For the settings of 1% and 10% labeled data fine-tuned evaluations as few-shot image recognition, we basically follow Semi-ViT in the context of semi-supervised learning [4].

A.2 MAE

Loss function. For the baseline MIM method, we selected MAE [4], which features computational efficiency and state-of-the-art performance in a wide range of downstream tasks. The MAE loss function is defined as

$$L^{mim}(\mathbf{z}^{pred}, \mathbf{x}^{masked}) = MSE(\mathbf{z}^{pred}, \mathbf{x}^{masked}), \quad (5)$$

where \mathbf{z}^{pred} is output from an auxiliary decoder.

Implementation details. Table 2 shows the implementation details for MAE alone and MAE with mask-guided attention bias in the first phase shown in Fig 1. We used the same settings as in He *et al.* [4]. Unlike DINO with mask-guided attention bias, we did not initially

freeze the mask-guided attention bias parameters as warm-up. Note that we set the mask size to 2×2 token size in the pretraining with ViT/8 [10]. Tables 4 and 6 show the evaluation settings for linear probing and full-data fine-tuning, which are the same as in He *et al.* [10]. For the settings of 1% and 10% labeled data fine-tuned evaluations, we used the same settings as Semi-ViT [10].

| Setting | Value |
|------------------------|---------------------------------------------------------------------------------------------|
| Optimizer | AdamW [10] |
| Batch size | 512 |
| Base learning rate | $2.5e-3$ |
| Warmup epochs | 10 |
| Learning rate schedule | cosine schedule [10] |
| Weight decay | 0.04 to 0.4 |
| Teacher temp | 0.04 to 0.07 |
| Momentum teacher | 0.996 to 1 |
| Augmentation | RandomResizedCrop, Color Jittering, Gaussian Blur, Solarization, RandomHorizontalFlip |

Table 1: DINO Pretraining settings

| Setting | Value |
|------------------------|--------------------------------|
| Optimizer | AdamW |
| Base learning rate | $1.5e-4$ |
| Optimizer momentum | $\beta_1, \beta_2 = 0.9, 0.95$ |
| Batch size | 4096 |
| Learning rate schedule | cosine schedule |
| Warmup epochs | 40 |
| Augmentation | RandomResizedCrop |
| Masking ratio | 0.75 |
| Masking strategy | Random |

Table 2: MAE Pretraining settings

| Setting | Value |
|------------------------|--------------------------------------------|
| Optimizer | SGD |
| Base learning rate | $1e-3$ |
| Optimizer momentum | 0.9 |
| Batch size | 256 |
| Learning rate schedule | cosine schedule |
| Training epochs | 100 |
| Augmentation | RandomResizedCrop, RandomHorizontalFlip |

Table 3: DINO Linear probing settings

| Setting | Value |
|------------------------|-------------------|
| Optimizer | LARS [10] |
| Base learning rate | 0.1 |
| Weight decay | 0 |
| Optimizer momentum | 0.9 |
| Batch size | 16384 |
| Learning rate schedule | cosine decay |
| Warmup epochs | 10 |
| Training epochs | 90 |
| Augmentation | RandomResizedCrop |

Table 4: MAE Linear probing settings

| Setting | Value |
|--------------------------------|---------------------------------|
| Optimizer | AdamW |
| Base learning rate | 1e-4 |
| Weight decay | 0.05 |
| Optimizer momentum | $\beta_1, \beta_2 = 0.9, 0.999$ |
| Layer-wise learning rate decay | 0.65 |
| Batch size | 256 |
| Learning rate schedule | cosine decay |
| Warmup epochs | 5 |
| Training epochs | 100 |
| Augmentation | RandAug (9, 0.5) [9] |
| Label smoothing [10] | 0.1 |
| Mixup [10] | 0.8 |
| Cutmix [10] | 1.0 |
| Drop path | 0.1 |
| Random erasing [10] | 0.25 |

Table 5: DINO Full-data fine-tuning settings

| Setting | Value |
|--------------------------------|--------------------------------|
| Optimizer | AdamW |
| Base learning rate | 1e-3 |
| Weight decay | 0.05 |
| Optimizer momentum | $\beta_1, \beta_2 = 0.9, 0.95$ |
| Layer-wise learning rate decay | 0.75 |
| Batch size | 1024 |
| Learning rate schedule | cosine decay |
| Warmup epochs | 5 |
| Training epochs | 100 |
| Augmentation | RandAug (9, 0.5) |
| Label smoothing | 0.1 |
| Mixup | 0.8 |
| Cutmix | 1.0 |
| Drop path | 0.1 |

Table 6: MAE Full-data fine-tuning settings

References

- [1] Zhaowei Cai, Avinash Ravichandran, Paolo Favaro, Manchen Wang, Davide Modolo, Rahul Bhotika, Zhuowen Tu, and Stefano Soatto. Semi-supervised vision transformers at scale. In *NeurIPS*, 2022.
- [2] Mathilde Caron, Hugo Touvron, Ishan Misra, Hervé Jégou, Julien Mairal, Piotr Bojanowski, and Armand Joulin. Emerging properties in self-supervised vision transformers. In *ICCV*, 2021.
- [3] Ekin Dogus Cubuk, Barret Zoph, Jon Shlens, and Quoc Le. Randaugment: Practical automated data augmentation with a reduced search space. In *NeurIPS*, 2020.
- [4] Quentin Duval, Ishan Misra, and Nicolas Ballas. A simple recipe for competitive low-compute self supervised vision models. *arXiv:2301.09451*, 2023.
- [5] Priya Goyal, Piotr Dollár, Ross Girshick, Pieter Noordhuis, Lukasz Wesolowski, Aapo Kyrola, Andrew Tulloch, Yangqing Jia, and Kaiming He. Accurate, large minibatch sgd: Training imagenet in 1 hour. *arXiv:1706.02677*, 2018.
- [6] Kaiming He, Xinlei Chen, Saining Xie, Yanghao Li, Piotr Dollár, and Ross Girshick. Masked autoencoders are scalable vision learners. In *CVPR*, 2022.
- [7] Ronghang Hu, Shoubhik Debnath, Saining Xie, and Xinlei Chen. Exploring long-sequence masked autoencoders. *arXiv:2210.07224*, 2022.
- [8] Ilya Loshchilov and Frank Hutter. SGDR: Stochastic gradient descent with warm restarts. In *ICLR*, 2017.
- [9] Ilya Loshchilov and Frank Hutter. Decoupled weight decay regularization. In *ICLR*, 2019.
- [10] Christian Szegedy, Vincent Vanhoucke, Sergey Ioffe, Jon Shlens, and Zbigniew Wojna. Rethinking the inception architecture for computer vision. In *CVPR*, 2016.
- [11] Yang You, Igor Gitman, and Boris Ginsburg. Large batch training of convolutional networks. *arXiv:1708.03888*, 2017.
- [12] Sangdoo Yun, Dongyoon Han, Seong Joon Oh, Sanghyuk Chun, Junsuk Choe, and Youngjoon Yoo. Cutmix: Regularization strategy to train strong classifiers with localizable features. In *ICCV*, 2019.
- [13] Hongyi Zhang, Moustapha Cisse, Yann N. Dauphin, and David Lopez-Paz. mixup: Beyond empirical risk minimization. In *ICLR*, 2018.
- [14] Zhun Zhong, Liang Zheng, Guoliang Kang, Shaozi Li, and Yi Yang. Random erasing data augmentation. In *AAAI*, 2020.