

Supplementary Materials for Enforcing Monotonous Shape Growth or Shrinkage in Video Segmentation

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1 Details about section 2.4 : Rewriting as a multi-label problem

We show now another point of view on sequence segmentation with growth constraint. The successive labels $L_i(t)$ of a given pixel i over time might change only once, and only from 0 (background) to 1 (foreground object). Hence, this vector of labels $L_i(t)$ is of the form $(0, 0, \dots, 0, 1, \dots, 1, 1)$ and can be represented by just the time index τ_i of the first 1, *i.e.* the earliest time at which the pixel starts belonging to the object. This time τ_i is in $[1, T + 1]$, with $T + 1$ meaning “never”. We have thus transformed a binary optimization problem on a sequence of images with shape growth constraint into a multi-label problem defined on one single image, without any constraint. This new problem can be expressed in the Markov Random Field form (1) with $V_i(\tau_i) := \sum_{t < \tau_i} V_i^t(0) + \sum_{t \geq \tau_i} V_i^t(1)$ and

$$W_{i,j}(\tau_i, \tau_j) := \sum_{t < \min(\tau_i, \tau_j)} W_{i,j}^t(0, 0) + \sum_{\tau_i \leq t < \tau_j} W_{i,j}^t(1, 0) + \sum_{\tau_j \leq t < \tau_i} W_{i,j}^t(0, 1) + \sum_{t \geq \max(\tau_i, \tau_j)} W_{i,j}^t(1, 1)$$

where (V_i^t) and $(W_{i,j}^t)$ define the energy E^t at time t , and where sets of summation may be empty. The submodularity of the binary interaction terms W^t in each frame implies the submodularity of the multilabel interaction term W , *i.e.*

$$W_{i,j}(\tau_1, \tau_2) + W_{i,j}(\tau'_1, \tau'_2) \leq W_{i,j}(\tau_1, \tau'_2) + W_{i,j}(\tau'_1, \tau_2)$$

for all labels satisfying $\tau_1 \leq \tau'_1$ and $\tau_2 \leq \tau'_2$. Thus this energy can be minimized globally efficiently with now standard techniques (e.g. [14]). Note that in the particular case where interaction terms W^t do not depend on t , the interaction term W of this multi-label energy above can be rewritten as a convex function g of $(\tau_i - \tau_j)$, and then Ishikawa's construction [14] can be applied. It turns out that the graph built this way is precisely the graph that we built in our initial binary multi-frame problem. Our initial formulation is however more flexible, in that interaction terms can depend on t , and more natural, in that inclusion constraints can easily be enforced in spatial or/and time subregions only, while this would not be expressible with the multi-label formulation.

References

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- [2] H. Ishikawa. Exact optimization for Markov random fields with convex priors. *TPAMI*, 25, October 2003.