Higher-order Co-occurrence Features based on Discriminative Co-clusters for Image Classification

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Motivation

Co-occurrence based image features have attracted keen attentions due to the promising performances for image classification tasks [1, 2, 3, 6, 7]. For extracting the co-occurrences, it is common to transform the quantitative data into qualitative data (symbols) by means of quantization (clustering) at first; e.g., continuous gradient orientation is coded into orientation bins [3], RGB colors are indexed [2] and local features are categorized into visual words [7]. Such point-wise clustering, however, is not necessarily suitable to characterize the pair-wise co-occurrences. And the higher-order co-occurrences beyond pair-wise has been rarely considered due to the exponential increase of the dimensionality by using those point-wise symbols. In this paper, we propose a method to extract image features based on effective higher-order co-occurrences. The proposed method constructs the co-clusters to discriminatively quantize joint primitive quantitative data, such as pair-wise pixel intensities, unlike the standard co-occurrence methods that utilize simple clusters trained in an unsupervised manner for quantizing point-wise data. The discriminative co-clusters effectively exploit the co-occurrence characteristics even by a fewer number of cluster components, resulting in low-dimensional co-occurrence features, which enables us to develop the higher-order cooccurrence features of feasible dimensionality.

Proposed method

Let $\mathcal R$ be the quantitative data space, $x_p \in \mathcal R$ be the quantitative data at pixel position p in an image plane. We consider the general form for extracting co-occurrences:

$$\mathbf{M} = \left\{ \sum_{\{\boldsymbol{p}, \boldsymbol{q}\} \in \mathbb{N}} \omega(\boldsymbol{p}, \boldsymbol{q}) g_k(x_{\boldsymbol{p}}, x_{\boldsymbol{q}}) \right\}_{k=1,\dots,D} \in \mathfrak{R}^D,$$

where $\mathbb N$ indicates the set of local neighbor pairs and ω is the weighting function on those pairs. We introduce the function $g_k(x_{\boldsymbol p},x_{\boldsymbol q}):\mathcal R\times\mathcal R\to \mathfrak R_+$ to assign the pair $(x_{\boldsymbol p},x_{\boldsymbol q})$ with the k-th cluster $(k=1,\cdots,D)$ in the joint space $\mathcal R\times\mathcal R$, called *co-cluster*. The co-clusters g_k directly measure the co-occurrences and we construct them in a discriminative manner.

Discriminative co-cluster (Fig. 1). Suppose a two-class problem of images I_n with the class label $y_n \in \{+1, -1\}$. From the image I_n , we first extract primitive co-occurrence features $\tilde{\mathbf{M}}_n$ on $\mathcal{R} \times \mathcal{R}$ as in GLCM [1]; in practice, the space R which is usually continuous is finely partitioned into (large number of) L bins, resulting in $\tilde{\boldsymbol{M}}_n \in \Re^{L \times L}$. Then, the *linear* SVM is applied to those $(\tilde{\boldsymbol{M}}_n, y_n)$ in order to produce the classifier weight \boldsymbol{W} on $\mathcal{R} \times \mathcal{R}$, actually $\mathbf{W} \in \mathfrak{R}^{L \times L}$. The classifier weight exploits the discriminative information: the positive weights in W contribute to '+1' class, while the negative ones to '-1' class. Finally, we perform clustering on the weight matrix W to produce the co-cluster assignment function g_k which is determined as the membership function to the k-th co-cluster on $\mathcal{R} \times \mathcal{R}$. We separately treat the weight \mathbf{W} in terms of its sign (positive/negative) as the positive weight $\mathbf{W}^+ = \max(\mathbf{W}, 0)$ and the negative $\mathbf{W}^- = \max(-\mathbf{W}, 0)$, $\mathbf{W} = \mathbf{W}^+ - \mathbf{W}^-$, and apply the EM clustering method [5] to those respective weights; the cluster component is represented by Gaussian function \mathcal{N}_k with the prior weights α_k . The function g_k is finally determined by

$$g_k(x_1, x_2) = \frac{\alpha_k \mathcal{N}_k(x_1, x_2)}{\sum_k \alpha_k \mathcal{N}_k(x_1, x_2)}, \ \forall x_1, x_2 \in \mathcal{R},$$

which is the posterior probability at (x_1, x_2) , resulting in the normalized g_k : $\sum_k g_k(x_1, x_2) = 1$.

Higher-order co-occurrence (Fig. 2). By using the co-clusters g_k , the proposed higher-order co-occurrence features are defined by

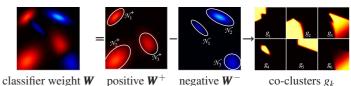
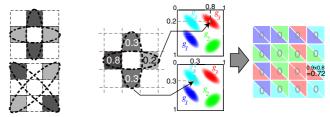


Figure 1: Construction of discriminative co-clusters g_k .



(b) *cross* quadruplet (c) higher-order co-occurrence Figure 2: Higher-order co-occurrence.

$$\boldsymbol{H} = \left\{ \sum_{\{\boldsymbol{p}, \boldsymbol{q}, \boldsymbol{r}, \boldsymbol{s}\} \in \mathbb{Q}} \omega(\boldsymbol{p}, \boldsymbol{q}, \boldsymbol{r}, \boldsymbol{s}) g_k(\boldsymbol{x}_{\boldsymbol{p}}, \boldsymbol{x}_{\boldsymbol{q}}) g_l(\boldsymbol{x}_{\boldsymbol{r}}, \boldsymbol{x}_{\boldsymbol{s}}) \right\}_{k,l = 1, \cdots, D} \in \mathfrak{R}^{D \times D},$$

where $\mathbb Q$ indicates the quadruplets. In this higher-order co-occurrence, it is important how to determine the quadruplets $\mathbb Q$, forms of which could be combinatorially increased. Co-occurrences are based on pairs which are oriented in various directions, and we configure the quadruplets, the pairs of pairs, in the form of *cross* as shown in Fig. 2a in order to extract diverse characteristics in image textures; the pairs in the cross are maximally (orthogonally) separated.

Results

We applied the proposed method to cancer detection using biopsy images [6] and pedestrian detection using the Daimler Chrysler dataset [4], both of which result in two class classifications. The primitive quantitative data x_p are pixel intensities for biopsy images and gradient orientations for pedestrian images. Even for smaller number of the co-clusters, D, the proposed method produces superior performances to the other methods, including the standard co-occurrence method; in equal error rate, 94.29% for cancer detection and 94.32% for pedestrian detection.

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