## Manifold-enhanced Segmentation through Random Walks on Linear Subspace Priors

Pierre Yves Baudin<sup>1,2,4,5,6</sup> pierre-yves.baudin@ecp.fr
Noura Azzabou<sup>5,6,7</sup>
n.azzabou@institut-myologie.org
Pierre Carlier<sup>5,6,7</sup>
p.carlier@institut-myologie.org
Nikos Paragios<sup>2,3,4</sup>
nikos.paragios@ecp.fr

Segmentation of skeletal muscles in 3D Magnetic Resonance Imaging, which poses some very specific issues: simultaneous multi-object segmentation, non-discriminative appearance of the muscles, partial contours between them, large inter-subject variations, spurious contours due to fat infiltrations. For these reasons, it is necessary to impose knowledgebased shape priors into segmentation methods. In [2, 3, 4], segmentation is achieved with multi-object elastical deformable models, using either a reference atlas or a hierarchical statistical prior model. A discrete optimization procedure on a graph framework is used in [7], where a higher-order pose invariant shape prior is imposed on surface landmarks nodes. A pixel-wise region-based approach was proposed in [1] where prior knowledge is enforced by embeding the model into a statistical lowdimensional non-linear manifold through PCA in the Isometric Log-Ratio space. Random Walks for image segmentation, presented in [6], is a numerical method for computing globally large discrete regions-based segmentation methods, and is notoriously robust to partial contours. Prior knowledge on intensity within the RW formulation was introduced in [5].

In this paper, we propose a segmentation method based on RW, in which shape deformation is constrained to remain close to a PCA shape space built from training examples. Using the PCA allows us to model complex non-rigid shape variations relying on a few eigen-modes. Our method also benefits from the high performances of the RW optimization process.

The RW method amounts to computing the probability  $x_i^s$  that the node  $v_i$  is assigned to the label s. It was shown ([6]) that this probabilities minimize the functional:

$$E_{\text{RW}}^{s}(x^{s}) = x^{sT}Lx^{s} \tag{1}$$

where L is the combinatorial Laplacian matrix of the graph, defined as:

$$\forall (i,j) \in \mathcal{E}, L_{ii} = \sum_{k} w_{ik}, L_{ij} = -w_{ij}.$$
 (2)

It is common practice to use as a Gaussian weighting function for  $w_{ij}$ . Once computed  $x^s$  for each label s, the segmentation is obtained by retaining the label of maximum probability:  $\hat{s}_i = \arg \max_s x_i^s$ .

Since minimizing (1) is an independent process for each label s, the whole RW process can be equivalently synthesized in one equation, via concatenation of the  $x^s$  and diagonal concatenation of L:

$$E_{\text{RW}}(x) = x^T \bar{L}x. \tag{3}$$

The principle of a shape space is to design a low dimensional affine [3] space approximating this implicit space. Assume we possess T co-registered segmented training volumes. We perform the PCA on vectors  $\{\hat{x}^i\}_{i=1...T}$ , which are ground truth segmentations represented as probability vectors. Retaining the n eigen-modes of greatest variance, the projection of any [4] segmentation in the shape space is represented as:

$$\tilde{x} = \bar{x} + \Gamma \gamma$$
.

Thus, any segmentation x can be expressed as:

$$x = dx + \Gamma \gamma + \bar{x} \tag{4}$$

where  $dx \in \mathbb{R}^{KN \times 1}$  is the deviation of x from the shape space.

In order to obtain a segmentation which remains close to the shape space, we want to minimize the objective function (3) with respect to

- <sup>1</sup> SIEMENS Healthcare, FR
- <sup>2</sup>Center for Visual Computing, FR
- <sup>3</sup> Université Paris-Est, FR
- <sup>4</sup> Equipe Galen, INRIA Saclay, FR
- <sup>5</sup> Institute of Myology, Paris, FR
- <sup>6</sup>CEA,IdM NMR Laboratory, Paris, FR
- <sup>7</sup>UPMC University Paris 06, FR







Figure 1: Effect of the PCA shape prior: (left) mean segmentation using  $x = \bar{x}$ , (middle) shape space segmentation using  $x = \Gamma \gamma + \bar{x}$ , (right) segmentation with shape prior using  $x = dx + \Gamma \gamma + \bar{x}$ . The shape space segmentation fits the boundaries better than the mean segmentation, but has fuzzy contours due to the approximation of projecting complex shapes into a linear subspace.

both dx and  $\gamma$ , while keeping dx small. This leads us to the following functional:

$$E_1(dx,\gamma) = (dx + \Gamma\gamma + \bar{x})^T \bar{L}(dx + \Gamma\gamma + \bar{x}) + \lambda \|dx\|^2.$$
 (5)

The minimum of (5) verifies:

$$(A^T \bar{L}A + \lambda B) y = A^T \bar{L}\bar{x}$$
 (6)

with:

$$y = \begin{bmatrix} dx \\ \gamma \end{bmatrix}, A = [I_{KN} \Gamma], B = \begin{bmatrix} I_{KN} & 0 \\ 0 & 0 \end{bmatrix}.$$
 (7)

The system of equations (6) can be solved with iterative methods like Bi-Conjugate Gradient. Computation time is approximately 15 min per segmentation on a 2.8 GHz Intel process with 4GB of RAM. We present results obtained with our method on a set of 3D MR volumes of muscles. Our data set is comprised of 30 volumes of the right thigh of healthy subjects, covering a wide range of ages and morphologies. On figure 1, we show the effect of the PCA shape prior on one example of our dataset.

- Shawn Andrews, Ghassan Hamarneh, Azadeh Yazdanpanah, Bahareh HajGhanbari, and W Darlene Reid. Probabilistic multi-shape segmentation of knee extensor and flexor muscles. In *MICCAI*, volume 14, pages 651–8. 2011.
- [2] Salma Essafi, Georg Langs, and Nikos Paragios. Hierarchical 3D diffusion wavelet shape priors. In *ICCV*, pages 1717–1724. IEEE, September 2009.
- [3] Benjamin Gilles and Nadia Magnenat-Thalmann. Musculoskeletal MRI segmentation using multi-resolution simplex meshes with medial representations. *Medical image analysis*, 14(3):291–302, June 2010
- [4] Benjamin Gilles and Dinesh K. Pai. Fast musculoskeletal registration based on shape matching. In *MICCAI*, volume 5242 of *Lecture Notes in Computer Science*, pages 822–829. January 2008.
- [5] L. Grady. Multilabel Random Walker Image Segmentation Using Prior Models. In *CVPR*, volume 1, pages 763–770, 2005.
- [6] Leo Grady. Random walks for image segmentation. *Pattern Analysis and Machine Intelligence*, 28(11):1768–1783, 2006.
- [7] Chaohui Wang, Olivier Teboul, Fabrice Michel, Salma Essafi, and Nikos Paragios. 3D knowledge-based segmentation using poseinvariant higher-order graphs. In MICCAI, volume 6363 of Lecture Notes in Computer Science, pages 189–196. 2010.