

Algebraic Line Search for Bundle Adjustment

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Appendix 1

We give details about how to solve the Two-way ALS. We want to find the best magnitudes $\{\alpha_P^*, \alpha_Q^*\}$ for the camera displacement Δ_P and the structure displacement δ_Q . The algebraic error we want to minimize is:

$$\tilde{\varepsilon}(\mathbf{x}) = \sum_{i,j} v_{ij} \| \mathbf{S} [\mathbf{q}_{ij}]_\times (\mathbf{P}_i + \alpha_P \Delta_{P_i}) (\mathbf{Q}_j + \alpha_Q \delta_{Q_j}) \|^2. \quad (1)$$

Nullifying partial derivatives of $\tilde{\varepsilon}(\mathbf{x})$ from 1 with respect to α_P and α_Q gives:

$$\begin{aligned} \frac{\partial \tilde{\varepsilon}}{\partial \alpha_Q} &= \sum_{i,j} (2a + 2c\alpha_P + 2d\alpha_P^2 + 2\alpha_Q\alpha_P(2e + f\alpha_P) + 2g\alpha_Q) = 0 \\ \frac{\partial \tilde{\varepsilon}}{\partial \alpha_P} &= \sum_{i,j} (2b + 2c\alpha_Q + 2e\alpha_Q^2 + 2\alpha_Q\alpha_P(2d + f\alpha_Q) + 2h\alpha_P) = 0 \end{aligned} \quad (2)$$

where

$$\begin{aligned} a &= \sum_{i,j} v_{ij} (\mathbf{P}_i \mathbf{Q}_j)^\top (\mathbf{S} [\mathbf{q}_{ij}]_\times \mathbf{P}_i \delta_{Q_j}) \\ b &= \sum_{i,j} v_{ij} (\mathbf{P}_i \mathbf{Q}_j)^\top (\mathbf{S} [\mathbf{q}_{ij}]_\times \Delta_{P_i} \mathbf{Q}_j) \\ c &= \sum_{i,j} v_{ij} (\mathbf{S} [\mathbf{q}_{ij}]_\times \mathbf{P}_i \delta_{Q_j})^\top (\mathbf{S} [\mathbf{q}_{ij}]_\times \Delta_{P_i} \mathbf{Q}_j) + (\mathbf{P}_i \mathbf{Q}_j)^\top (\Delta_{P_i} \delta_{Q_j}) \\ d &= \sum_{i,j} v_{ij} (\mathbf{S} [\mathbf{q}_{ij}]_\times \Delta_{P_i} \mathbf{Q}_j)^\top (\Delta_{P_i} \delta_{Q_j}) \\ e &= \sum_{i,j} v_{ij} (\mathbf{S} [\mathbf{q}_{ij}]_\times \mathbf{P}_i \delta_{Q_j})^\top (\Delta_{P_i} \delta_{Q_j}) \\ f &= \sum_{i,j} v_{ij} (\Delta_{P_i} \delta_{Q_j})^\top (\Delta_{P_i} \delta_{Q_j}) \\ g &= \sum_{i,j} v_{ij} (\mathbf{S} [\mathbf{q}_{ij}]_\times \mathbf{P}_i \delta_{Q_j})^\top (\mathbf{S} [\mathbf{q}_{ij}]_\times \mathbf{P}_i \delta_{Q_j}) \\ h &= \sum_{i,j} v_{ij} (\mathbf{S} [\mathbf{q}_{ij}]_\times \Delta_{P_i} \mathbf{Q}_j)^\top (\mathbf{S} [\mathbf{q}_{ij}]_\times \Delta_{P_i} \mathbf{Q}_j) \end{aligned}$$

Solving the polynomial system (2) with the MAPLE Buchberger's algorithm gave us the following solutions :

$$\{\alpha_P^*, \alpha_Q^*\} = \{p, \frac{-a - cp - dp^2}{g + 2ep + fp^2}\} \quad (3)$$

with $p = RootsOf(F(X))$ and $F : \mathbb{R} \rightarrow \mathbb{R}$ is a degree 5 polynomial:

$$\begin{aligned} F(X) = & (-hf^2 + d^2f) X^5 \\ & +(3ed^2 - 4hef + cdf - bf^2) X^4 \\ & +(-4he^2 - 4bef - 2hfg + 4cde + 2d^2g) X^3 \\ & +(c^2e - 4heg - 4be^2 + 2ead - 2bfg - caf + 3cdg) X^2 \\ & +(c^2g + 2dag - 4beg - fa^2 - hg^2) X \\ & -bg^2 - ea^2 + cag. \end{aligned}$$